

## EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	3317275	(stereoscopic or 3D or three adh dimensional\$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:00
L2	479792	(stereoscopic or 3D or three adj dimensional\$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:14
L3	2470	L2 same (plurality or plural\$1)same camera	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:01
L4	361	L2 same (plurality or plural\$1)same camera same angle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:06
L5	7	L4 same calculat\$3 near3(disparity or range or intensity or depth)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:13
L6	2	L5 and @ad<"20010910"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:05
L7	0	L6 and registers and clock near3 signal	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:05
L8	12	L4 and registers and clock near3 signal	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:04
L9	0	L8 and calculat\$3 near3(disparity or range or intensity or depth)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:05

## EAST Search History

L10	12	L8 and calculat\$3 and(disparity or range or intensity or depth)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:10
L11	9	L10 and @ad<"20010910"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:13
L12	9	L11 and registers and clock near3 signal	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:05
L13	9	L12 and(plurality or plural\$1)same camera same angle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:06
L14	6	L13 and (first and second)same memory	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:14
L15	0	L2 and calculat\$3 near3(disparity or range or intensity or depth)same (plurality or plural\$1)same image\$1 same register\$3 same clock near3 signal	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:12
L16	0	(3D or three adj dimensional\$1 or 3-D )and calculat\$3 near3(disparity or range or intensity or depth)same (plurality or plural\$1)same image\$1 same register\$3 same clock near3 signal	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:13
L17	163	(3D or three adj dimensional\$1 or 3-D )and calculat\$3 near3(disparity or range or intensity or depth)and(plurality or plural\$1)and image\$1 and register\$3 and clock near3 signal	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:13
L18	123	L17 and @ad<"20010910"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:13

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L19	123	L18 and calculat\$3 near3(disparity or range or intensity or depth)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:14
L20	81	L19 and (first and second)same memory	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:14
L21	80	L20 and(steroscopic or 3D or three adj dimensional\$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:14
L22	54	L21 and (match\$3 or compar\$ or combin\$4)and (decision or evaluat\$3 or jude\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/07/05 17:16